# Visible/Near-IR vs. Uncooled Long Wave Infrared Automatic Target Recognition

Lower Cost of ATR/Fusion by 100 Times

Extend Range Non Conventional Targets

(for Collaborative Technology Alliance - Army Research Lab & IR&D)

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### First ATR Flight Trials

	1970s	1980s	1990s	2000s
FLIR	*			
SAR		*		
Fusion			*	
Visible*				

<sup>\* 6.1</sup> Exploratory Research

#### Vis-NIR vs. Uncooled FLIR ATR

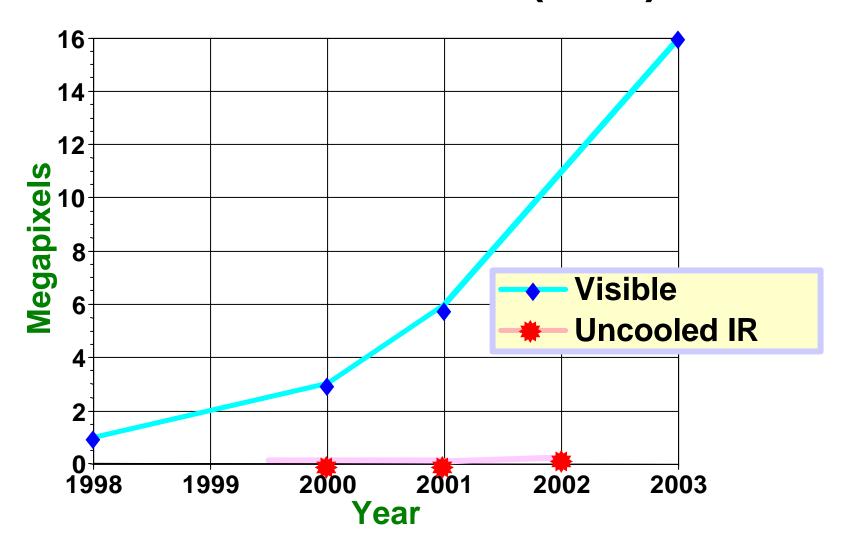
#### Case for Vis-NIR

- Sensor Cost: VIS-NIR=0.02¢/pixel vs. Uncooled FLIR=40¢/pixel
- Commercial base: HDTV, camcorders, digital cameras, JPEG, MPEG, etc.
- Military vehicles have 4 times reflectivity in NIR as compared to visible
- FLIR does not work well at mid-day

#### Case for Uncooled FLIR (long wave infrared)

- Military vehicles are painted to defeat recognition in visible (but not NIR!)
- Cost may be high, but still much less than cooled 2nd gen FLIR
- Active targets "pop-out" at night
- Long wave IR not affected by solar reflections
- Cleaner psd function than 2nd gen FLIR systems

### Small Cameras (~1lb)



# Small FLIR 15° VFOV, 120 lines (Unmanned Ground Station scenario)

Lines	<b>计数据</b> 图	No.	16.00	No. of Park
on				
Target		F 255.85	1 10.00	126.4
U	18	12	8	6
Range	51	77	116	154
to	meters	meters	meters	meters
Target				

# Data Collections Vis/NIR vs. Uncooled FLIR

5 in 2001 3 planned for 2002 air-to-ground, ground-to-ground short range (UGS, small UAV) (<1 km) long range (> 1km)

### Visible & Near-IR







Kodak 620x, 720x

Nikon D1, D1x, etc.

3rd gen intensifier

# Uncooled FLIR



FLIR Sys. PM695



Mikron 7200



Indigo Omega
(not tested yet)

#### **Illuminators**



Xenonics

NightHunter



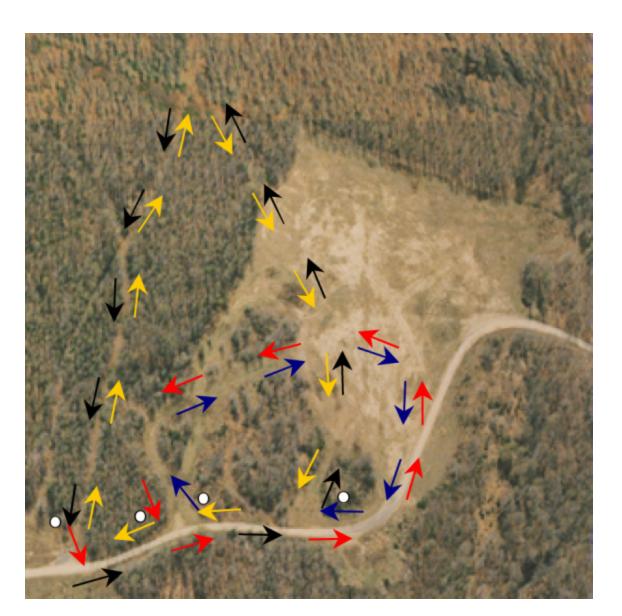
Gilway

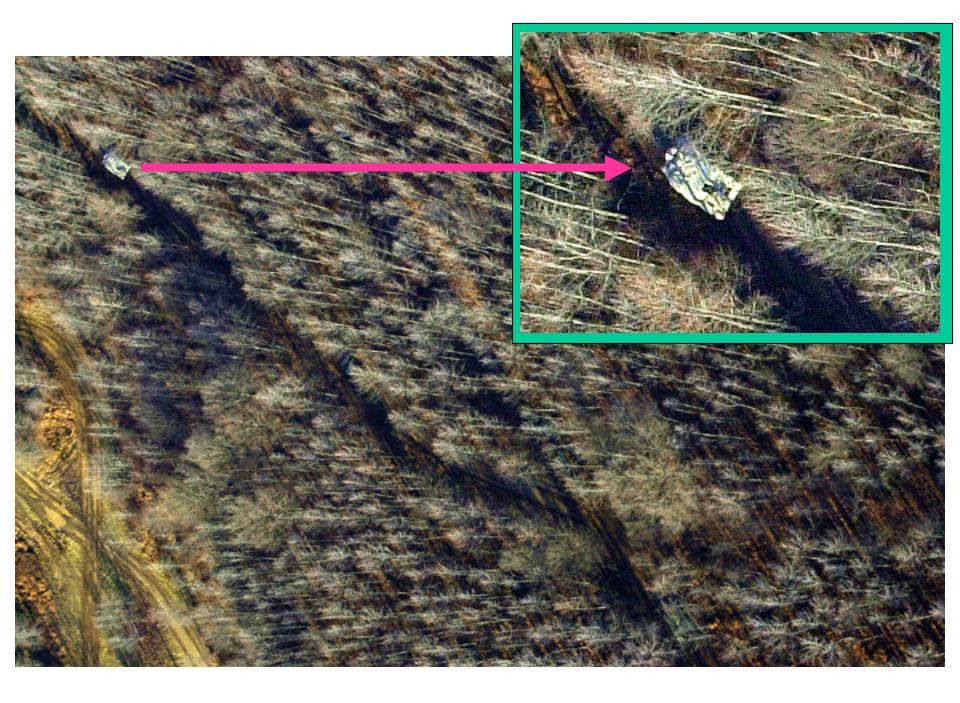


GE



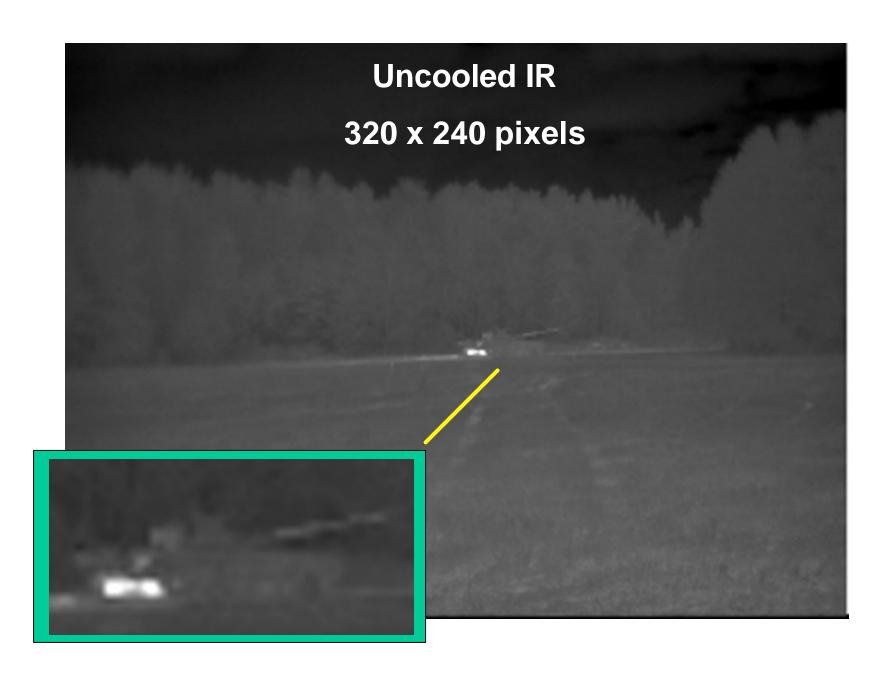
### Scenario B



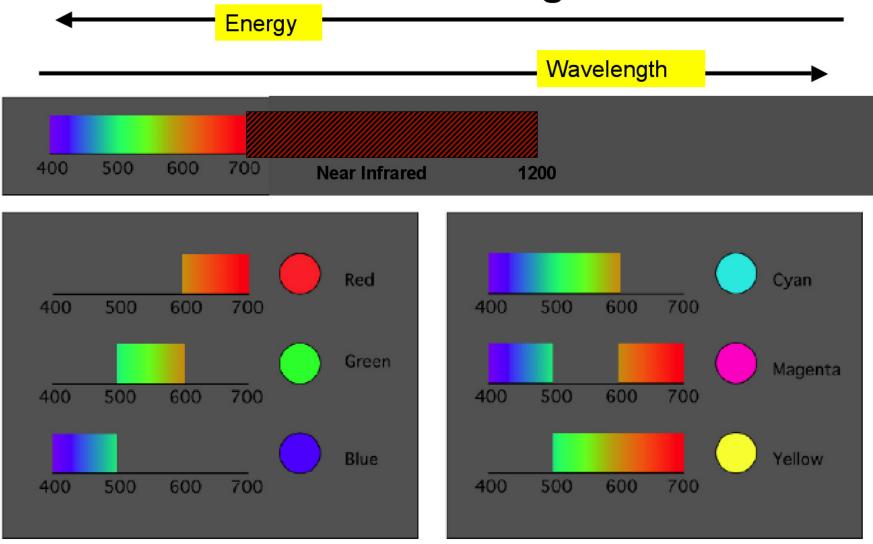


# 3008 x 1960 pixels Nikon D1x



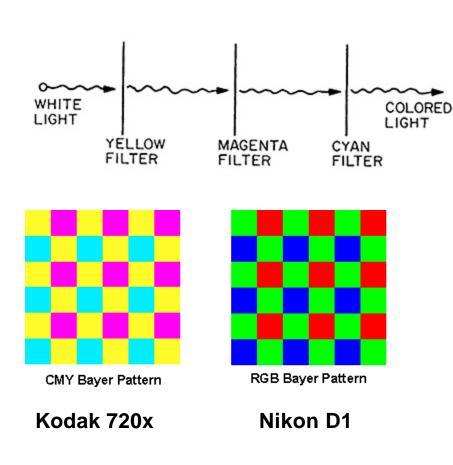


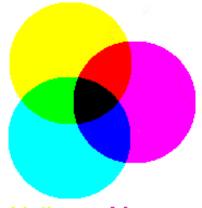
# What Bands are Best for Target Detection and Recognition?



#### {Red, Green, Blue} vs. {Cyan, Magenta, Yellow}

White light is passed through cyan, magenta, and yellow filters.





Red = Yellow + Magenta

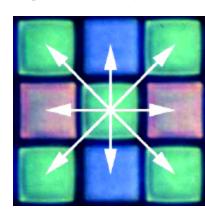
Green = Yellow + Cyan

Blue = Magenta + Cyan

Vector

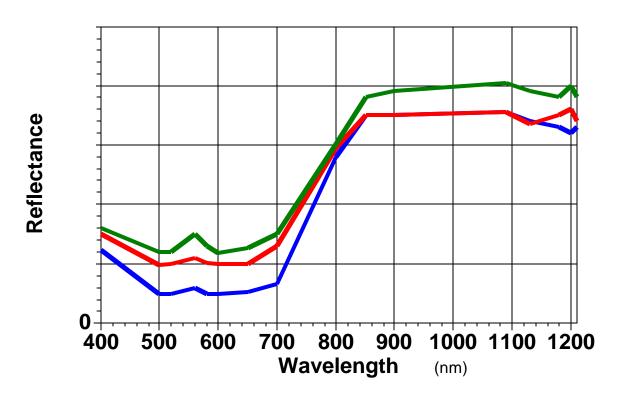
**Pixels** 

(Green = low noise)



### Importance of Near IR Component

Vis-NIR Spectral Response of 3 Samples of Green CARC Paint



From: "Surface Reflectance Variations of Realistic Targets",

D. Thomas, R. Evans, J. Crosby, TACOM

### Vis/NIR Band Choices

- Magenta
- Yellow
- Near infrared (or visible + near IR)

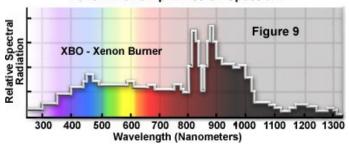
#### **Active Near IR Illumination**

#### Xenon





#### Xenon Arc Lamp Emission Spectrum

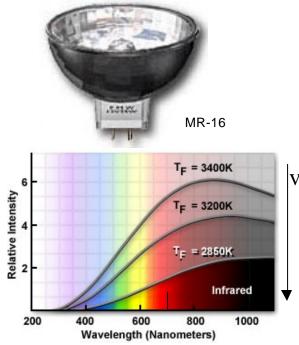


Xenonics Illuminator: Tested 75watt, 10° beam, at 200 meters, 1/30 sec. Note beam goes to 1°.

Guide 200 flash attachment

-> 200 ft range for ISO 100 Or >1 km at ISO 25000

#### Halogen



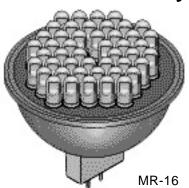
4, 8, 10, or 12 degree beam

Aluminum reflector (non dichroic)

12v, 50-100 watt

14,000 candela vis. (65w, 10°, \$9); 65,000 candela (4°)

#### IR LED Array

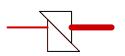


850, 880, or 950 nm 12 degree beam 12 volt, 4 watts equiv. 200 candela \$120

### What's New

#### **Laser Spot**

1500 nm

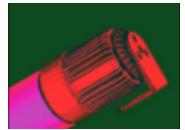


~0.5°

4.3m high at 500m

## Halogen with Gold Reflector

Highest IR Reflectivity







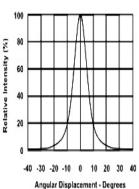
 $\sim$ 2°, 100 watt ==> Range > .5km

~ 500,000 candela

#### **Luxeon Star LED**

Highest in-band illumination per watt





825 candela on axis

### Approaches to Target Detection

a m

a g



Leopard in Tree



**Snow Rabbit** 

- Anomaly Detection (for SAR & long wave IR but not visible)
- Change Detection (for moving targets)
- Pattern Detection (Gestalt ={scale, shape, edges & texture})

# Target Detection (single frame) IR vs. Visible (UGS Day Scenario)



Visible

**Target Not Detected** 



Uncooled Long Wave IR

Very Strong Detection



Magenta, Yellow, NIR

Strong Detection

Much

Rarer

Case



Visible

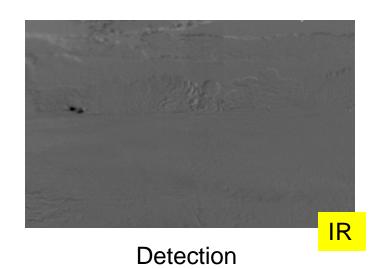
Very Strong Detection

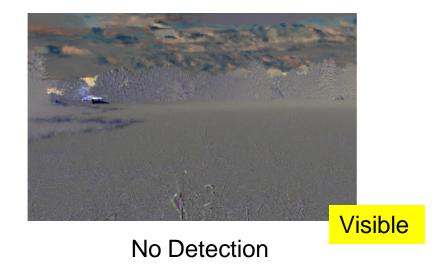


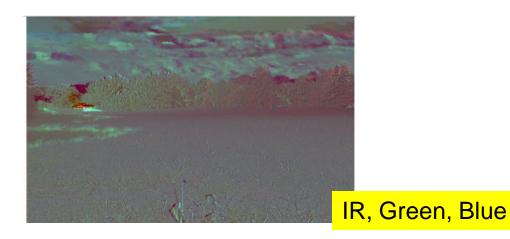
Uncooled Long Wave IR

Target Not Detected

# Moving Target Detection Simple 2-Frame Change Detection







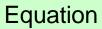
#### Simple Multi-frame Change Detection



Fifth image of moving BTR-70.



Moving target detection image  $\Delta$ .



$$\Delta = |\mathbf{t}_{i} - \mathbf{t}_{i-1}| + |\mathbf{t}_{i} - \mathbf{t}_{i-2}| + |\mathbf{t}_{i} - \mathbf{t}_{i-3}|$$

$$+ |\mathbf{t}_{i} - \mathbf{t}_{i-4}| - |\mathbf{t}_{i-2} - \mathbf{t}_{i-4}| - |\mathbf{t}_{i-1} - \mathbf{t}_{i-3}|$$



Target at full resolution

D image

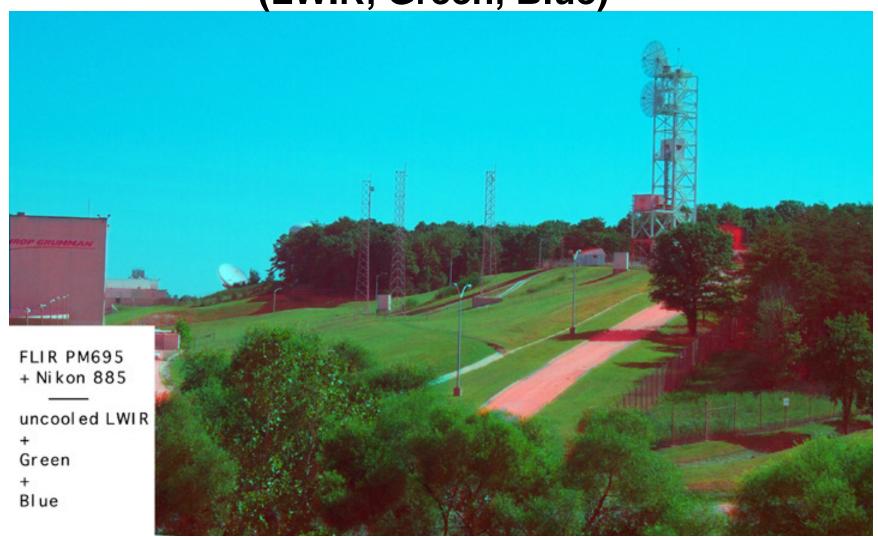
#### **Approaches to Fusion (Visible + FLIR)**

- Pixel Level fusion ==> multi-band
- Feature Level fusion
- Post declaration fusion
- Plug in sensor based on conditions

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- Single sensor multi-look fusion
- trade temporal for spatial bandwidth

Fusion of Visible and Uncooled FLIR (LWIR, Green, Blue)

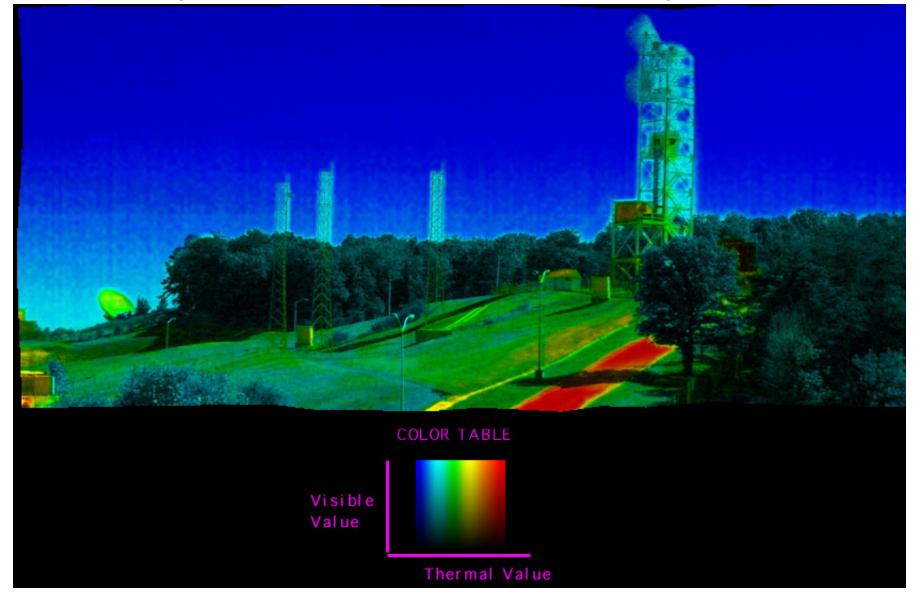


## Fusion of Visible and Uncooled FLIR (I WIR Green Blue)

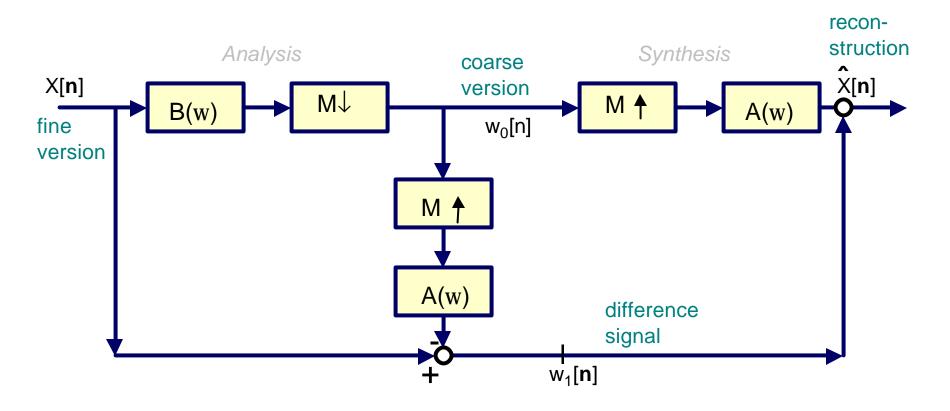


#### **Fusion of Vis and Uncooled FLIR**

(Treating each pixel as vector {Vis,LWIR} and mapping to false color)

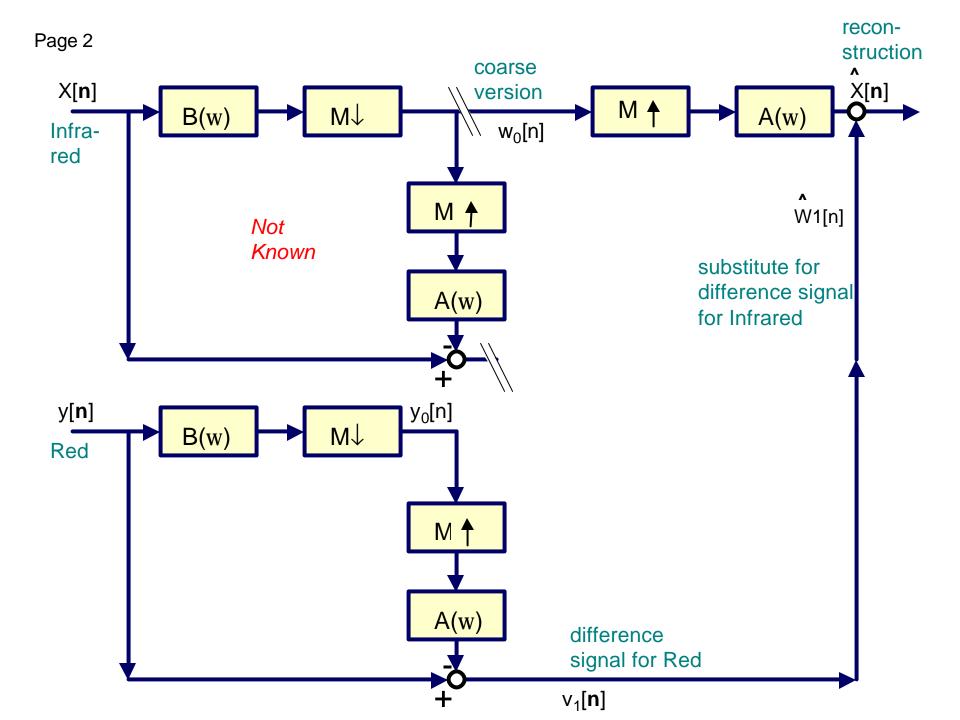


#### Resolution Enhancement of Microbolometer Data - page 1



Construction of one level of Laplacian pyramid.

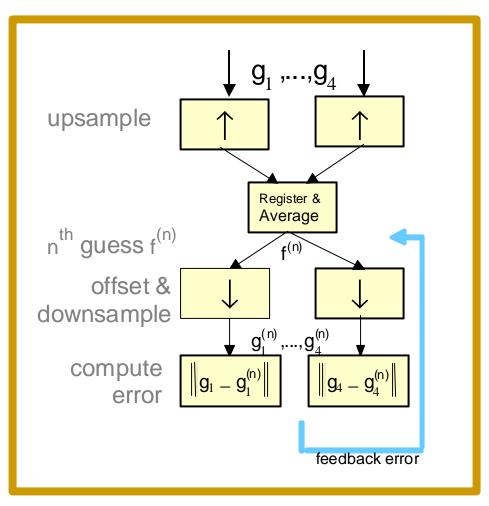
This transformation may also be described as an analysis/synthesis filter bank.

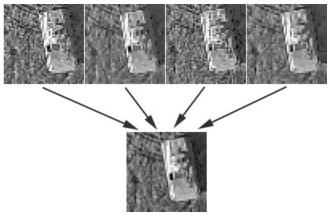


# Embedding Detail from Ultra-high Resolution Vis-NIR into Uncooled FLIR



# Multi-frame Super-Resolution of Uncooled FLIR Data





#### Vis/NIR vs. Uncooled Long Wave IR - Early Conclusions

- Conclusions do not hold under all conditions
- And are not backed by government blind tests as with other sensors
- {Magenta, Yellow, Near IR} better for ATR than {Red, Green, Blue}
- Simple anomaly detection works better in LWIR than Visible bands
- Simple change detection works better in LWIR than Visible bands
- But, targets can be detected in Vis/NIR using pattern and change analysis.
- Uncooled LWIR is particularly good for detection, but doesn't supply detail for recognition beyond moderate range.
- Visible / Near IR can be fused with Uncooled LWIR for little extra cost